

# CLUSTERIZATION FOR DERIVING EIGENPAIRS OF A VIBRO-ACOUSTIC RECTANGULAR CAVITY

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Considerable efforts have been made with a view to deriving the eigenpairs of a strongly coupled rectangular cavity comprising a flexible panel and five rigid walls, which has frequently been employed as a target model for discussing transmission loss of a cavity-backed panel. The eigenpairs of even such a simplistic cavity however have not been found for decades. The reason is obvious: a spatial boundary condition of a distributed parameter system made it difficult to solve the eigenvalue problem. Just recently, the authors succeeded in deriving the eigenpairs of the strongly coupled rectangular cavity by introducing a cluster functions that may tackle the spatial boundary condition. As a result of coupling, two kinds of acoustic modes are found to appear; standing wave mode and evanescent mode. The former is generated by sound reflections in the cavity, whereas the latter by coupling effect. It is likely that the dimensions of a characteristic matrix of a coupled cavity increase because of a distributed parameter system being dealt with. This paper then presents a clusterization method in order to reduce the computation burden. For this purpose, it is shown that the characteristic matrix of a cavity is dominated by a coupling coefficient matrix. Inasmuch as coupling is strictly selective, the coupling matrix is found to be expressed in a form consisting of four independent cluster matrices. It is shown that the eigenpairs of the coupled cavity may then be obtained by aggregating eigenpairs of each cluster.

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## 1. Introduction

The term “coupling” indicates interference between a structural and an acoustic field of a cavity, resulting in the shift of the eigenpairs of uncoupled system dynamics. Depending on the degree of coupling, cavity systems can be classified into two categories: a weakly coupled cavity system (or a modally coupled cavity) system and a strongly coupled cavity system.

A weakly coupled cavity system often introduced in sound transmission control problems [for instance, 1,2] is based on the modal coupling theorem established under the assumption that the fluid medium is non-dense and the cavity walls not “thin.” The characteristic of this system is that the eigenfunctions of a coupled system remain the same as those of an acoustically rigid walled cavity, while only the eigen-frequencies of the cavity change.

When cavity walls become thin and the cavity gap shallow, the assumption of a modal coupling is no longer valid; thus, such a case falls into the second category, i.e., a strongly coupled cavity system. Considerable efforts have been made in literature to derive the exact solution of coupled rectangular cavity system that comprises five rigid walls and a flexible panel. Dowell and Voss [3] expressed the sound pressure acting on a cavity-backed panel as a linearized form of Bernoulli’s equation; Pretlove [4], in an attempt to spatially match the structural and acoustic mode shapes, introduced a cosine series expansion for simulating the cavity-backed panel deflection which is originally expressed as a sine-sine function, however, convergence of the method was not shown; Tanaka *et al.* [5-7] presented

a set of cluster functions falling on the category of essentially degenerate eigenfunctions possessing the same eigen-frequency in common, deriving explicitly the eigenpairs of a strongly coupled cavity. Employing the cluster function, Tanaka *et al.* [8, 9] succeeded in deriving the eigenpairs of a strongly coupled eigenpairs, clarifying its fundamental properties.

This paper begins by overviewing the eigenpairs derivation of a strongly coupled rectangular cavity comprising five rigid walls and one flexible panel which Tanaka *et al.* derived [8, 9]. The basic characteristics of the eigenpairs of a strongly coupled cavity are then deciphered with a particular emphasis on an evanescent cavity mode emerging as a result of strongly coupling between an acoustic field and a structural field. It is likely that the dimensions of a characteristic matrix of a coupled cavity increase because of a distributed parameter system being dealt with. With a view to overcoming this problem, this paper then presents a clusterization method which may reduce the computation burden. It is shown that the characteristic matrix of a cavity is dominated by a coupling coefficient matrix. Inasmuch as coupling is strictly selective, the coupling matrix is found to be expressed in a form consisting of four independent cluster matrices. It is then shown that the eigenpairs of the coupled cavity may be obtained by merely aggregating eigenpairs of each cluster.

## 2. Eigenpairs of a strongly coupled rectangular cavity and clusterization

### 2.1 Overview of eigenpairs derivation of a strongly coupled rectangular cavity

Consider a rectangular cavity comprising a flexible panel placed on the top and five acoustically rigid walls as shown in Fig.1

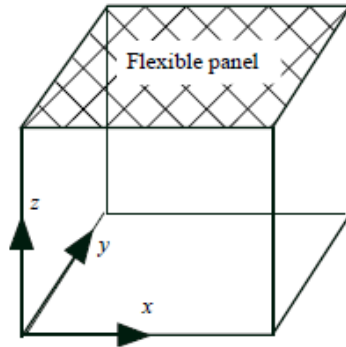


Figure 1: Rectangular cavity model with a flexible panel on the top

Sound wave equation in the cavity may then be written as

$$c^2 \nabla^2 \bar{\phi}(x, y, z) + \bar{\omega}^2 \bar{\phi}(x, y, z) = 0 \quad (1)$$

where  $c$ ,  $\bar{\phi}$ ,  $\bar{\omega}$  denote the sound speed, velocity potential and eigenvalue after coupling. Note that a bar in the expression implies parameters after coupling. Since the above is a homogeneous equation so that as a whole the solution to Eq.(1) may not be written using an expansion theorem, however we dare to introduce the expansion theorem using a cluster function  $\tilde{\phi}_i$  as

$$\bar{\phi}(x, y, z) = \sum a_i \tilde{\phi}_i(x, y, z) \quad (2)$$

where the cluster function satisfies the following homogeneous sound wave equation

$$c^2 \nabla^2 \tilde{\phi}_i(x, y, z) + \bar{\omega}^2 \tilde{\phi}_i(x, y, z) = 0 \quad \forall i \quad (3)$$

Equation (3) denotes that the cluster function is an essentially degenerated eigenfunction with the common eigenvalue  $\bar{\omega}$ , and hence the superposition of the cluster functions satisfies the homogeneous sound wave equation. The cluster function is further decomposed to

$$\tilde{\phi}_i(x, y, z) = \psi_i(x, y)\eta_i(z) \quad (4)$$

where

$$\psi_i(x, y) = \cos \frac{l_i \pi}{L_x} x \cos \frac{m_i \pi}{L_y} y \quad (l_i, m_i = 0, 1, 2, 3 \dots) \quad (5)$$

$$\eta_i(z) = \cos \gamma_{l_i m_i} z \quad (6)$$

whereby the sound wave equation may be rewritten as

$$\left( \frac{l_i \pi}{L_x} \right)^2 + \left( \frac{m_i \pi}{L_y} \right)^2 + \gamma_{lm}^2 = \frac{\bar{\omega}^2}{c^2} \quad (7)$$

Equation of motion of a panel may be written as

$$D \nabla^4 \bar{v}(x, y) - \bar{\omega}^2 \rho h \bar{v}(x, y) = \bar{\omega}^2 \rho_a \bar{\phi}(x, y, z) \Big|_{z=L_z} \quad (8)$$

where  $D$ ,  $\bar{v}$ ,  $\rho$ ,  $h$ ,  $\rho_a$  are flexural rigidity, surface velocity, density of the panel, thickness of the panel, and air density, respectively. The above is intrinsically homogeneous equation, however because of a coupling effect, the panel behaves in a manner that is subjected to sound pressure from inside the cavity which acts as an external force, hence Eq.(8) may then be expressed using an expansion theorem,

$$\bar{v}(x, y) = \sum_{i=1}^n b_i \varphi_i(x, y) \quad (9)$$

where  $\varphi_i$  is the *in vacuo*  $i$ th vibration modal function that satisfies

$$D \nabla^4 \varphi_i(x, y) - \omega_i^2 \rho h \varphi_i(x, y) = 0 \quad (10)$$

and where  $\omega_i$  is the associated eigen frequency.

Next, spatial boundary condition is given by

$$v(x, y) = \frac{\partial}{\partial z} \bar{\phi}(x, y, z) \Big|_{z=L_z} \quad (11)$$

Using the expansion theorem, the equation of motion of a panel may then be described as

$$\sum_{\kappa=1}^n (\omega_{\kappa}^2 - \bar{\omega}^2) \rho h b_{\kappa} \varphi_{\kappa}(x, y) = \bar{\omega}^2 \rho_a \sum_{\kappa=1}^m a_{\kappa} \tilde{\phi}_{\kappa}(x, y, L_z) = \bar{\omega}^2 \rho_a \sum_{\kappa=1}^m a_{\kappa} \psi_{\kappa}(x, y) \eta_{\kappa} \quad (12)$$

Likewise, the boundary condition may also be written as

$$\sum_{\kappa=1}^n b_{\kappa} \varphi_{\kappa}(x, y) = \sum_{\kappa=1}^m a_{\kappa} \psi_{\kappa}(x, y) \eta_{\kappa}'(L_z) \quad (13)$$

In order to exclude the dependency of location in Eq.(13), it is common practice to multiply the  $s$ th *in vacuo* eigenfunction of the panel on both sides of Eq.(13), and then integrate over the panel domain, hence

$$b_s \frac{S}{4} = \frac{\rho_a \bar{\omega}^2}{\rho h (\omega_s^2 - \bar{\omega}^2)} \sum_{\kappa=1}^m a_{\kappa} \beta_{s\kappa} \eta_{\kappa}(L_z) \quad (14)$$

Equation (14) may also be expressed in a matrix form as

$$\mathbf{b} = \mathbf{\Lambda}_{\omega} \mathbf{B} \mathbf{\Lambda}_{\eta} \mathbf{a} \quad (15)$$

where

$$\mathbf{\Lambda}_\eta = \begin{pmatrix} \eta_1 & & & \mathbf{0} \\ & \eta_2 & & \\ & & \ddots & \\ \mathbf{0} & & & \eta_n \end{pmatrix} \quad (16)$$

$$\mathbf{B} = \begin{pmatrix} \cdots & \vdots & \cdots \\ \cdots & \beta_{ij} & \cdots \\ \cdots & \vdots & \cdots \end{pmatrix} \quad (17)$$

The boundary condition in Eq.(13) may also be written as

$$b_s \frac{S}{4} = \sum_{\kappa=1}^m a_\kappa \beta_{s\kappa} \eta'_\kappa(L_z) \quad (18)$$

The above equation may then be expressed in a matrix form as

$$\mathbf{b} = \mathbf{B}\mathbf{\Lambda}_\eta \mathbf{a} \quad (19)$$

where a coupling coefficient may be defined as

$$\beta_{s\kappa} = \int \varphi_s(x, y) \psi_\kappa(x, y) dx dy \quad (20)$$

Combining Eq.(15) and Eq.(19), the characteristic matrix equation of a strongly coupled rectangular cavity is produced.

$$(\mathbf{\Lambda}_\omega \mathbf{B}\mathbf{\Lambda}_\eta - \mathbf{B}\mathbf{\Lambda}_{\eta'}) \mathbf{a} = \mathbf{0} \quad (21)$$

or

$$\mathbf{M}\mathbf{a} = \mathbf{0} \quad (22)$$

Now that the characteristic equation is obtained in Eq.(22), the next stage is to search eigenvalues such that the determinant  $\mathbf{M}$  is zero. Once eigenvalues are searched, the eigenvectors may also be obtained.

## 2.2 Clusterization for deriving the eigenpairs

Equation (22) may further be written in detail as

$$\begin{pmatrix} m_{11} & m_{12} & \cdots & m_{1m} \\ m_{21} & m_{22} & \cdots & m_{2m} \\ \vdots & \vdots & \vdots & \vdots \\ m_{n1} & m_{n2} & \cdots & m_{nm} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{pmatrix} = \mathbf{0} \quad (23)$$

where

$$m_{s\kappa} = \left[ \frac{\rho_a \bar{\omega}^2}{\rho h (\omega_s^2 - \bar{\omega}^2)} \eta_\kappa(L_z) - \eta'_\kappa(L_z) \right] \beta_{s\kappa} \quad (24)$$

To solve an eigenvalue problem in Eq.(22), the matrix  $\mathbf{M}$  must be square, hence  $n = m$ . The procedure to seek the eigenpairs is straightforward. First, find a frequency that satisfies the determinant of  $\mathbf{M}$  being zero. With the eigenvalue, the eigenvector may then follows.

In general, the dimension of  $\mathbf{M}$  tends to be large due to a distributed parameter system dealt with, hence it is worth simplifying the structure of the eigenvalue problem of a strongly coupled cavity. Note that every term  $m_{sk}$  in Eq.(24) contains the coupling coefficient  $\beta_{sk}$ , hence the property of the matrix  $\mathbf{M}$  is dominated by the coupling coefficient matrix  $\mathbf{B}$ . The coupling coefficient  $\beta_{sk}$  indicates the coupling magnitude between the  $s$ th vibration mode and the  $k$ th acoustic mode. To further simplify the eigenvalue problem, we are now going to introduce a cluster coupling method.

Assume that all the vibration modes are classified into cluster  $\bar{A}, \bar{B}, \bar{C}$  and  $\bar{D}$  while the acoustic cut-on modes are clustered into  $\bar{a}, \bar{b}, \bar{c}$  and  $\bar{d}$ . Due to the coupling characteristics, the cluster  $\bar{A}$  couples only with  $\bar{a}$ , and  $\bar{B}$  for  $\bar{b}$ ,  $\bar{C}$  for  $\bar{c}$  and  $\bar{D}$  for  $\bar{d}$ ; e.g. odd/odd structural mode couples only with even/even acoustic mode. Define that

$$n = n_{\bar{A}} + n_{\bar{B}} + n_{\bar{C}} + n_{\bar{D}} \quad (25)$$

$$m = m_{\bar{a}} + m_{\bar{b}} + m_{\bar{c}} + m_{\bar{d}} \quad (26)$$

where for instance  $n_{\bar{A}}$  in the above denotes the number of structural modes belonging to the cluster A. Then, due to the properties of a cluster filtering, the matrix  $\mathbf{M}$  in eq.(22) may be partitioned into

$$\begin{pmatrix} \mathbf{M}_{\bar{A}} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}_{\bar{B}} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{M}_{\bar{C}} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{M}_{\bar{D}} \end{pmatrix} \begin{pmatrix} \mathbf{a}_{\bar{A}} \\ \mathbf{a}_{\bar{B}} \\ \mathbf{a}_{\bar{C}} \\ \mathbf{a}_{\bar{D}} \end{pmatrix} = \mathbf{0} \quad (27)$$

where

$$\mathbf{M}_{\bar{A}} \in \mathbb{C}^{n_{\bar{A}} \times m_{\bar{a}}}, \mathbf{M}_{\bar{B}} \in \mathbb{C}^{n_{\bar{B}} \times m_{\bar{b}}}, \mathbf{M}_{\bar{C}} \in \mathbb{C}^{n_{\bar{C}} \times m_{\bar{c}}}, \mathbf{M}_{\bar{D}} \in \mathbb{C}^{n_{\bar{D}} \times m_{\bar{d}}}$$

Moreover, Eq.(27) may be reduced to

$$\mathbf{M}_{\bar{A}} \mathbf{a}_{\bar{a}} = \mathbf{0} \quad (28)$$

$$\mathbf{M}_{\bar{B}} \mathbf{a}_{\bar{b}} = \mathbf{0} \quad (29)$$

$$\mathbf{M}_{\bar{C}} \mathbf{a}_{\bar{c}} = \mathbf{0} \quad (30)$$

$$\mathbf{M}_{\bar{D}} \mathbf{a}_{\bar{d}} = \mathbf{0} \quad (31)$$

It is clear that, from Eq.(28) through Eq. (31), a large dimensioned characteristic equation in (22) is partitioned into four clusters, and hence the burden to search for eigenpairs is significantly allayed.

Moreover, the eigenpairs of a strongly coupled rectangular cavity are independently as well as individually obtained in each cluster, hence the total eigenpairs may be in a form of merely aggregating the eigenpairs of each cluster.

It is also clear that in order for an eigenvalue problem to hold, matrices  $\mathbf{M}_{\bar{A}}, \mathbf{M}_{\bar{B}}, \mathbf{M}_{\bar{C}}$  and  $\mathbf{M}_{\bar{D}}$  need to be square, hence  $n_{\bar{A}} = m_{\bar{a}}, n_{\bar{B}} = m_{\bar{b}}, n_{\bar{C}} = m_{\bar{c}}, n_{\bar{D}} = m_{\bar{d}}$ . Recall that the condition,  $n = m$ , was needed to solve the eigenpairs problem, however, it turns out that it is the necessary condition, and not sufficient one. In other words,  $n_{\bar{A}}, n_{\bar{B}}, n_{\bar{C}}$  and  $n_{\bar{D}}$  need not to be equal. In the case where  $n_{\bar{A}} \neq m_{\bar{a}}$ , for instance, the number of structural mode or acoustic mode should be adjusted such that  $\mathbf{M}_{\bar{A}}$  being square.

### 3. Numerical analysis

Consider a rectangular cavity comprising flexible panel placed on top and five acoustically rigid walls with the dimension of ( $L_x = 0.18m, L_y = 0.38m, L_z = 0.866m, h = 0.8mm$ ). In this case, clusters  $\bar{A}, \bar{B}, \bar{C}, \bar{D}$  correspond to the cluster of (odd/odd structural modes and even/even acoustic

modes), (odd/even structural modes and even/odd acoustic modes), (even/odd structural modes and odd/even acoustic modes) and (even/even structural modes and odd/odd acoustic modes), respectively. First, we need to obtain eigenfrequencies of the vibration mode of a panel and cut on mode of a cavity.

Table 1 shows the modal indices of structural mode and acoustic cut-on mode placed in order of frequency. Consider for instance the case where  $s = \kappa = 1$ , which refers to an odd/odd structural mode, cluster A, and even/even acoustic cut on mode, hence the coupling coefficient  $\beta_{11}$  is non-zero hence  $\varepsilon_{11}$  is non-zero also. This fact is reflected in the eigenvalue matrix in Eq.(32)

Table 1: modal indices of structural modes and acoustic cut on modes in order of the frequency where  $s$  refers to structural mode and  $\kappa$  to acoustic cut on mode

indices	1	2	3	4	5	6	7	8	9	10
s	11	12	13	21	14	22	23	15	24	16
$\kappa$	00	01	02	10	11	12	03	13	04	20

$$\begin{pmatrix} 11 \\ 12 \\ 15 \\ 21 \\ 14 \\ 22 \\ 23 \\ 15 \\ 24 \\ 16 \end{pmatrix} \begin{pmatrix} 00 & 01 & 02 & 10 & 11 & 12 & 03 & 13 & 04 & 20 \\ m_{11} & & m_{13} & & & & & & m_{19} & m_{110} \\ & m_{22} & & & & m_{27} & & & & \\ m_{31} & & m_{33} & & & & & m_{39} & m_{310} & \\ & & & m_{44} & & m_{46} & & & & \\ & m_{52} & & & & & m_{57} & & & \\ & & & & m_{65} & & & m_{68} & & \\ & & & m_{74} & & m_{76} & & & & \\ m_{81} & & m_{83} & & & & & m_{89} & m_{810} & \\ & & & m_{95} & & & m_{98} & & & \\ & m_{102} & & & & & & m_{107} & & \end{pmatrix} \begin{pmatrix} a_1^{00} \\ a_2^{01} \\ a_3^{02} \\ a_4^{10} \\ a_5^{11} \\ a_6^{12} \\ a_7^{03} \\ a_8^{13} \\ a_9^{04} \\ a_{10}^{20} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad (32)$$

As a result of properly arranging the order of a row and a column in the above, we have

$$\begin{pmatrix} m_{11} & m_{13} & m_{17} & m_{110} \\ m_{31} & m_{33} & m_{37} & m_{310} \\ m_{81} & m_{83} & m_{87} & m_{810} \\ & & & \\ & m_{22} & m_{27} & \\ & m_{52} & m_{57} & \\ & m_{102} & m_{107} & \\ & & & \\ & & m_{44} & m_{46} \\ & & m_{74} & m_{76} \\ & & & \\ & & & m_{65} & m_{68} \\ & & & m_{95} & m_{98} \end{pmatrix} \begin{pmatrix} a_1^{00} \\ a_3^{02} \\ a_9^{04} \\ a_{10}^{20} \\ a_2^{01} \\ a_7^{03} \\ a_4^{10} \\ a_6^{12} \\ a_5^{11} \\ a_8^{13} \end{pmatrix} = \mathbf{0} \quad (33)$$

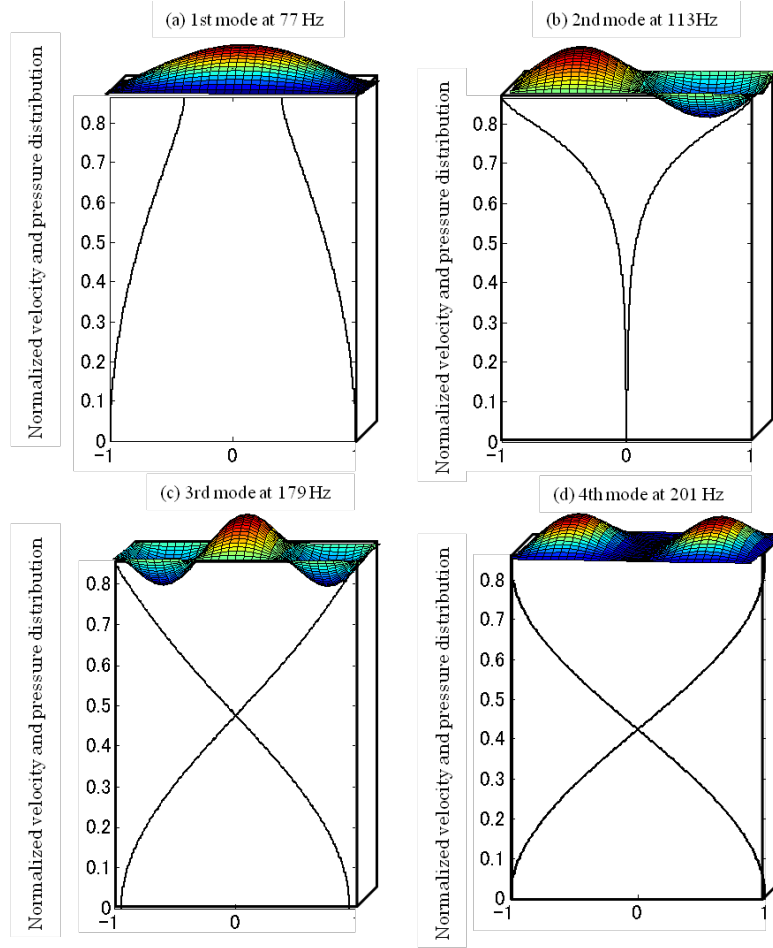


Figure 2: Normalized velocity mode shape of a flexible panel and the acoustic mode shapes in the cavity at the 1<sup>st</sup> ~ 4<sup>th</sup> coupled mode [8, 9]

Illustrated in Fig.2 are the normalized velocity mode shapes of a flexible panel of the coupled rectangular cavity [8, 9]. Observe that the structural modal behaviours from the 1<sup>st</sup> through 3<sup>rd</sup> mode are dominated by the *in vacuo* mode shape; (1,1), (1,2) and (1,3) mode, respectively. As for the 4<sup>th</sup> mode, however, the original *in vacuo* structural (2,1) mode is replaced by the deformed (1,3) mode because of the coupling effect. Figure 2 also shows the corresponding acoustic mode shapes along the  $z$  direction depicted using the expression: in Eq.(2) in the vicinity of  $x = L_x / 2$  and  $y = L_y / 2$ . Unlike the acoustic mode shapes observed in a rigid wall, the mode shapes in the  $z$  direction appear different. Regarding the first mode at 77 Hz in Fig.2(a), although the rigid wall mode shape is depicted by two parallel straight lines along the  $z$  axis, the acoustic mode shape after coupling shrinks as  $z$  increases, leading to that of an open ended cavity at  $z = L_z$  as an extreme case. Acoustic mode shapes in Figs.2(c) and (d) are similar to each other, albeit the 4<sup>th</sup> mode is considerably affected by the coupling effect. Note that among the four in Fig.2, the 2<sup>nd</sup> acoustic mode shape appears different from the ordinary mode shapes. Such an intriguing mode shape, characteristic of a strongly coupling effect between the vibrational and acoustic fields, emerges when the eigenvalue after coupling becomes smaller than the cut-on frequency.



## 4. Conclusions

The derivation of the eigenpairs of a strongly coupled rectangular cavity comprising a flexible panel placed on top and acoustically rigid five walls was presented, fundamental properties of the eigenpairs being discussed. It was shown that, as a result of coupling between a structural field and acoustic field in the cavity, two kinds of acoustic modes are found to appear; standing wave mode and evanescent mode. The former is generated by sound reflections in the cavity, whereas the latter by coupling effect. It is likely that the dimensions of a characteristic matrix of a coupled cavity increase because of a distributed parameter system being dealt with. This paper then presented a clusterization method in order to reduce the computation burden on deriving the eigenpairs of a strongly coupled cavity. For this purpose, it was shown that the characteristic matrix of a cavity is dominated by a coupling coefficient matrix. Inasmuch as coupling is strictly selective, the coupling matrix is found to be expressed in a form consisting of four independent cluster matrices. The eigenpairs of the coupled cavity may then be obtained by aggregating eigenpairs of each cluster. Finally, a numerical example was demonstrated, verifying the validity of the proposed clusterization approach.

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